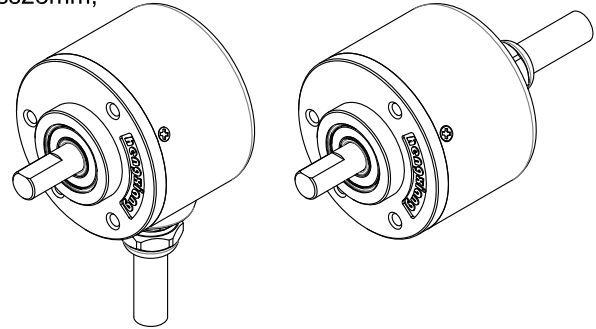


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Specifications 1/4

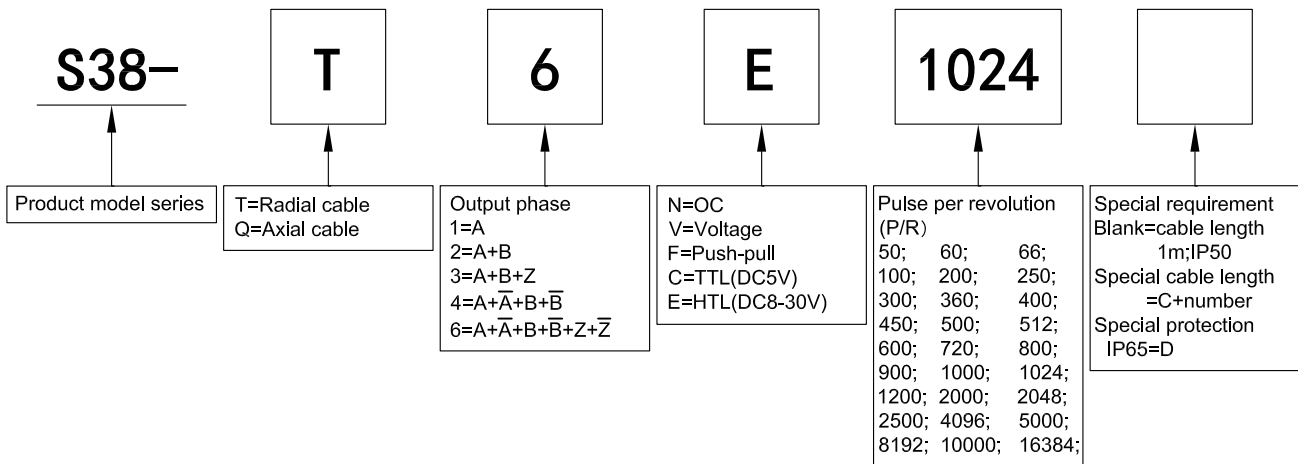
Incremental Type(Solid shaft)

- Feature: general,small,optional various output mode, long service life,low price,etc
- Application: textile industry、 packing machinery、 production line , ect , for automation control
- External dimensions: external diameter Ø38mm,thickness28mm, diameter of shaft 6mm(D type)
- Resolution: up to 16384P/R
- Supply voltage: DC5V; DC8-30V
- Protection: IP50; IP65
- Cable length: 1000mm
- Weight: about 120g



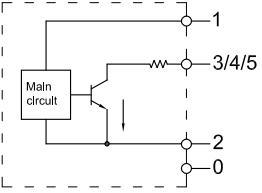
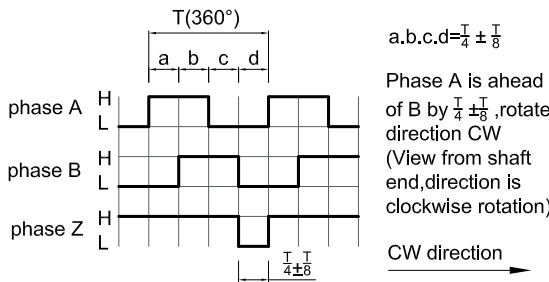
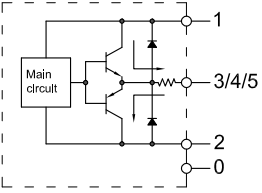
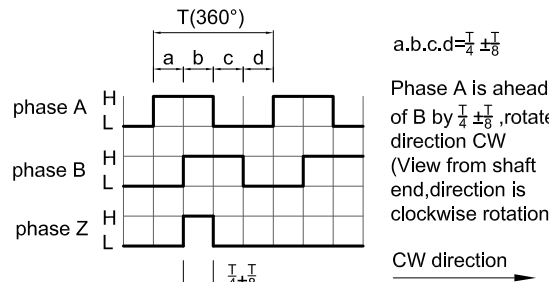
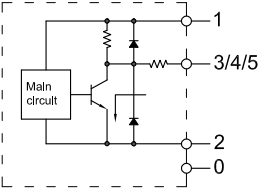
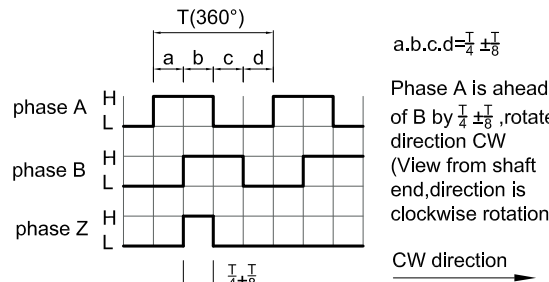
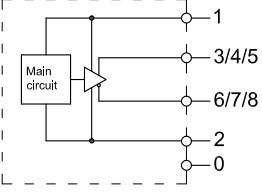
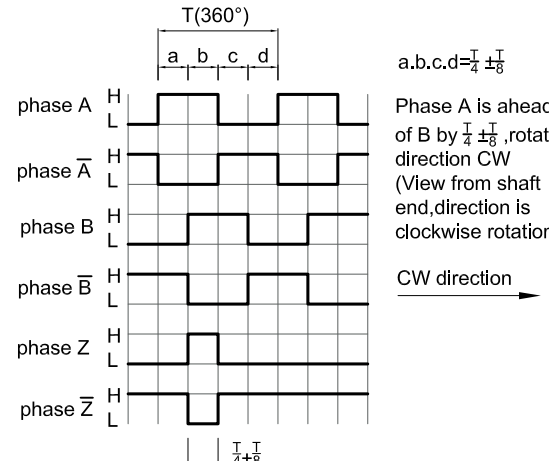
Model Guide

- Model form (filled required parameters in the box as following)



- Must choose supply voltage: DC5V; DC8-30V
- If need coupling ,please purchase additionally (Please refer to accessory at specifications 4/4)

Output Mode

Output type	Output circuit	Output wave form	Connection
OC		 <p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotate direction CW (View from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	0=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z
Push-Pull		 <p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotate direction CW (View from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	
Voltage		 <p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotate direction CW (View from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	
TTL		 <p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotate direction CW (View from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	0=shielding=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z 6=white/black= \bar{A} 7=green/black= \bar{B} 8=yellow/black= \bar{Z}
HTL			

■ Electrical Characteristics

Parameter Item	Output type	OC		Voltage		Push-pull		TTL		HTL			
Supply voltage		DC+5V±5%; DC8V-30V±5%						DC+5V±5%		DC8-30V±5%			
Consumption current		100mA Max											
Allowable ripple		≤3%rms											
Top response frequency		100KHz				200KHz				300KHz			
Output volume	Output current	Input	≤30mA		Load resistance 2.2K	≤30mA		≤±20mA		≤±50mA			
		Output	—			≤10mA							
	Output voltage	"H"	—		—		≥[(Supply voltage)-2.5V]		≥2.5V		≥V _{CC} -3 V _{DC}		
		"L"	≤0.4V		≤0.7V(less than 20mA)		≤0.4V(30mA)		≤0.5V		≤1V V _{DC}		
	Load voltage	≤DC30V		—				—					
Rise & Fall time		Less than 2us(cable length: 2m)						Less than 1us (Cable length: 2m)		≤100ns			
Insulation strength		AC500V 60s											
Insulation resistance		10MΩ											
Mark to space ratio		45% to 55%											
Phase shift between A & B		90°±10° (low speed,frequency ≤1000Hz)											
		90°±20° (high speed,frequency >1000Hz)											
Origin motion		Low level available		High level available		Low level available		—					
GND		not connect to encoder											

■ Mechanical Characteristics

Shaft	∅6mm D type(stainless steel)
Starting torque	Less than 4.4×10^{-3} N·m
Inertia moment	Less than 1.5×10^{-6} kg·m ²
Shaft load	Radial 40N; Axial 20N
Slew speed	≤5000 rpm; IP65≤3000 rpm
Bearing Life	1.5×10^9 revs at rated load(100000hrs at 2500RPM)
Shell	Die cast aluminum
Weight	about 120g

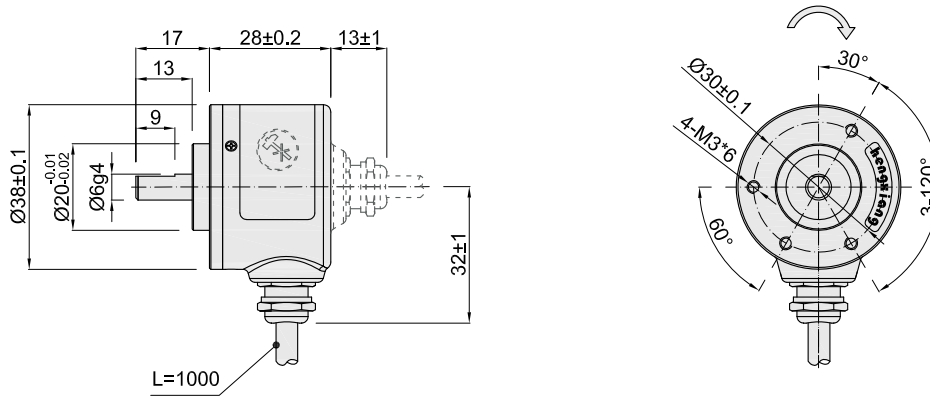
■ Environmental Specifications

Environmental temperature	Operating: -20~+90°C(repeatable winding cable: -10°C); Storage: -25~+100°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(endure)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(endure)	490m/s ² 11ms three times for X,Y,Z direction individually
Protection	IP50; IP65

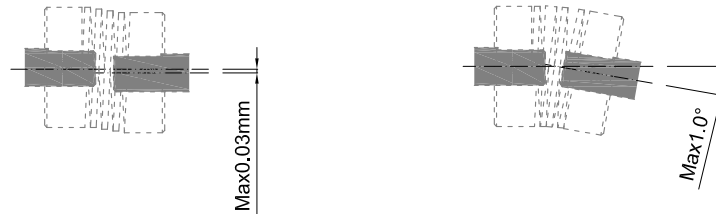
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Specifications 4/4

Basic Dimensions



Assembling requirement

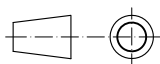


Notice : coaxiality between shaft of encoder and power shaft must be less than 0.03mm, and gradient must be less than 1.0°.

Accessory (Need purchase additionally)

H series oldham coupling (general accuracy, or choose M series for higher accuracy) 6H6 No:8700021 6H8 No:8700022			Model	D1	D2
			6H6	Ø6 ^{+0.01} / _{+0.03}	Ø6 ^{+0.01} / _{+0.03}
			6H8		Ø8 ^{+0.01} / _{+0.03}
material: aluminium alloy					
M series oldham coupling 6M6 No:8700037 6M8 No:8700038			Model	D1	D2
			6M6	Ø6 ^{+0.01} / _{+0.03}	Ø6 ^{+0.01} / _{+0.03}
			6M8		Ø8 ^{+0.01} / _{+0.03}
material: aluminium alloy					

Unit: mm



= Rotate direction of signal output shaft

About vibration

Vibration act on encoder always cause wrong pulse , so we should pay attention to working place.
 More pulse per revolution , narrower groovy spacing of grating , more effect to encoder by vibration, when rev is low or stop , vibration act on shaft or main body would cause grating vibrating , so encoder might make wrong pulse .